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14MAR/MAU/IAE/MDE/MMD/MST/MTH/MTP11

**First Semester M.Tech. Degree Examination, Dec.2016/Jan.2017
Applied Mathematics**

Time: 3 hrs.

Max. Marks:100

Note: Answer any FIVE full questions.

- 1 a. Define with suitable examples: i) Significant figure; ii) Round off error; iii) Truncation error; iv) Inherent error; v) Relative error. (10 Marks)
- b. The differential equation governing velocity of a falling parachutist is given by $\frac{dv}{dt} = g - \left(\frac{c}{m}\right)v$, where g-acceleration due to gravity, m-mass of parachutist, c-drag coefficient, obtain analytical solution at t = 10 sec. Also, obtain finite difference approximation in steps of 2 sec till t = 10sec, assuming v(0) = 0. Data: g = 9.8, m = 68.1, c = 12.5. (10 Marks)
- 2 a. Write important steps of bisection method to find the root of the equation f(x) = 0. Also, find a real root of the equation $x \sin x + \cos x = 0$ by using Newton-Raphson method, where $x_0 = 3\pi/4$. (10 Marks)
- b. Apply Muller's method to find the root of the equation $x^3 - 3x - 5 = 0$ which lies in [2, 3]. (10 Marks)
- 3 a. Find all the roots of $x^3 - 4x^2 + 5x - 2 = 0$ by Graffe's root squaring method. (10 Marks)
- b. Perform two iterations of the Bairstow method to extract a quadratic factor $x^2 + px + q$ from the polynomial $x^3 + x^2 - x + 2 = 0$. Use the initial approximations $P_0 = -0.9, q_0 = 0.9$. (10 Marks)
- 4 a. Find the minimum value of y from the table:

x:	3	4	5	6	7	8
y:	0.205	0.240	0.259	0.262	0.250	0.224

 (10 Marks)
- b. Use Romberg's method to compute $\int_0^1 \frac{dx}{1+x^2}$, correct to 4 decimal places, by taking h = 0.5, 0.25 and 0.125. (10 Marks)
- 5 a. Solve the system of linear equations $x_1 + 2x_2 + 3x_3 = 5; 2x_1 + 8x_2 + 22x_3 = 6$ and $3x_1 + 22x_2 + 82x_3 = -10$ by using Cholesky method. (10 Marks)
- b. Using partition method, find the inverse of the matrix

$$\begin{bmatrix} 1 & 1 & 1 \\ 4 & 3 & -1 \\ 3 & 5 & 3 \end{bmatrix}$$
 (10 Marks)

Important Note: 1. On completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages.
2. Any revealing of identification, appeal to evaluator and /or equations written eg, 42+8 = 50, will be treated as malpractice.

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- 6 a. Use Jacobi's method to find all the eigen values and the eigen vectors of the matrix

$$\begin{bmatrix} 2 & \sqrt{2} & 4 \\ \sqrt{2} & 6 & \sqrt{2} \\ 4 & \sqrt{2} & 2 \end{bmatrix}$$

(10 Marks)

- b. Transform the matrix $A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 1 & -1 \\ 3 & -1 & 1 \end{bmatrix}$ to tridiagonal form by given method. Use exact arithmetic.

(10 Marks)

- 7 a. Let $A = \begin{bmatrix} 1 & -3 \\ 3 & 5 \\ -1 & 7 \end{bmatrix}$, $u = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$, $b = \begin{bmatrix} 3 \\ 2 \\ -5 \end{bmatrix}$ and define a transformation $T : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ by

$$T(X) = AX, \text{ so that } T(X) = AX = \begin{bmatrix} 1 & -3 \\ 3 & 5 \\ -1 & 7 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 - 3x_2 \\ 3x_1 + 5x_2 \\ -x_1 + 7x_2 \end{bmatrix}.$$

- i) Find $T(u)$, the image of u under the transformation T .
 ii) Find an X in \mathbb{R}^2 whose image under T is b . **(06 Marks)**
- b. Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transformation. Then T is one-to-one if and only if the equation $T(X) = 0$ has only the trivial solution. **(06 Marks)**
- c. In a certain region, about 5% of the city's population moves to the surrounding suburbs each year, and about 4% of the suburban population moves into the city. In 2000, there were 600,000 residents in the city and 400,000 in the suburbs. Set up a difference equation that describes this situation, where x_0 is the initial population in 2000. Then estimate the population in the city and in the suburbs two years later, in 2002. **(08 Marks)**

- 8 a. Let $y = \begin{bmatrix} 7 \\ 6 \end{bmatrix}$ and $u = \begin{bmatrix} 4 \\ 2 \end{bmatrix}$. Find the orthogonal projection of y onto u . Then write y as the sum of two orthogonal vectors, one in $\text{span}\{u\}$ and one orthogonal to u . **(06 Marks)**

- b. Show that $\{v_1, v_2, v_3\}$ is an orthonormal basis of \mathbb{R}^3 , where

$$v_1 = \begin{bmatrix} 3/\sqrt{11} \\ 1/\sqrt{11} \\ 1/\sqrt{11} \end{bmatrix}, v_2 = \begin{bmatrix} -1/\sqrt{6} \\ 2/\sqrt{6} \\ 1/\sqrt{6} \end{bmatrix}, v_3 = \begin{bmatrix} -1/\sqrt{66} \\ -4/\sqrt{66} \\ 7/\sqrt{66} \end{bmatrix}.$$

(04 Marks)

- c. Find a least-squares solution of $Ax = b$ for

$$A = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 1 \end{bmatrix}, b = \begin{bmatrix} -3 \\ -1 \\ 0 \\ 2 \\ 5 \\ 1 \end{bmatrix}.$$

(10 Marks)